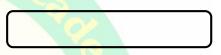
Test Booklet Series

ELECTRONICS & TELECOMMUNICATION ENGINEERING (OBJECCTIVE TYPE) PAPER – II



INSTRUCTIONS

- 1. IMMEDIATELY AFTER THE COMMENCEMENT OF THE EXAMINATION, YOU SHOULD CHECK THAT THIS TEST BOOKLET DOES NOT HAVE ANY UNPRINTED OR TORN OR MISSING PAGES OR ITEMS, ETC. IF SO, GET IT REPLACED BY A COMPLETE TEST BOOKLET.
- 2. ENCODE CLEARLY THE TEST BOOKLET SERIES **A**, **B**, **C** OR **D** AS THE CASE MAY BE IN THE APPROPRIATE PLACE IN THE ANSWER SHEET.
- 3. You have to enter your Roll Number on the Test Booklet in the Box provided alongside. *DO NOT* write *anything else* on the Test Booklet



- 4. This Test Booklet contains 120 items (questions), 60 in PART A and 60 in PART B. Each item comprises four responses (answers). You will select the response which you want to mark on the Answer Sheet. In case you feel that there is more than one correct response, mark the response which you consider the best. In any case, choose ONLY ONE response for each item.
- 5. You have to mark all your responses *ONLY* on the separate Answer Sheet provided. See directions in the Answer Sheet.
- 6. All items carry equal marks
- 7. Before you proceed to mark in the Answer Sheet the response to various items in the Test Booklet, you have to fill in some particulars in the Answer Sheet as per instructions sent to you with your Admission Certificate.
- 8. After you have completed filling in all your responses on the Answer Sheet and the examination has concluded, you should hand over to the Invigilator *only the Answer Sheet*. You are permitted to take away with you the Test Booklet.
- 9. Sheets for rough work are appended in the Test Booklet at the end.

10. Penalty for wrong answers:

THERE WILL BE PENALTY FOR WRONG ANSWERS MARKED BY A CANDIDATE IN THE OBJECTIVE TYPE QUESTION PAPERS.

- (i) There are four alternatives for the answer to every question. For each question for which a wrong answer has been given by the candidate, **one-third (0.33)** of the marks assigned to that question will be deducted as penalty.
- (ii) If a candidate gives more than one answer, it will be treated as a **wrong answer** even if one of the given answers happiness to be correct and there will be same penalty as above to that question.
- (iii)If a question is left blank, i.e. no answer is given by the candidate, there will be **no penalty** for that question.

- 01. The threshold effect in demodulators is
 - (a) The rapid fall of output SNR when the input SNR falls below a particular value
 - (b) Exhibited by all the demodulators when the input SNR is low
 - (c) Exhibited by all AM suppressed carrier coherent demodulators
 - (d) Exhibited by correlation receivers

Ans: (a)

02. An amplitude modulated signal is

[$A + 0.5 A \cos \omega_m t$] $\cos \omega_c t$ where ω_m and ω_c are respectively, modulating and carrier frequencies. The power efficiency is

- (a) 11.11% (b) 0.25% (c) 4.32% (d) 50% Ans : (a)
- 03. The signal $x(t) = \sin(200 \pi t) + 2\sin(400\pi t)$ is modulated to produce a signal $g(t) = x(t) \sin(400 \pi t)$.

This is passed through a low pass filter having a cut-off frequency of 400π Hz and pass band gain of 2. Then the output signal after the filter is

(a) 0 (b) $0.5 \sin(200\pi t)$ (c) $\sin(200\pi t)$ (d) $2 \sin(200\pi t)$

Ans: (b)

- 04. In communication systems, noise due to quantization error is
 - (a) Linear and signal dependent
 - (b) Non-linear and signal dependent
 - (c) Linear and signal independent at low frequencies only
 - (d) non-linear and signal dependent at low frequencies only

Ans: (a)

05. Match List I with List II and select the correct answer using the code given below the lists:

| | List | I | n, | | List II |
|----------------------------|----------|----------|--------|---|--|
| A. Cha | racteria | stic imp | edance | | 1. ∇ . D = ρ_V |
| B. Poyr | nting v | ector | | | 2. $\sqrt{\frac{j\omega\mu}{(\sigma + j\omega\varepsilon)}}$ |
| C. Disp | lacem | ent curr | ent | | 3. E × H |
| D. Point form of Gauss law | | | | | $24. \frac{\partial \mathbf{D}}{\partial t}$ |
| Codes | | | | | |
| | А | В | С | D | |
| (a) | 2 | 3 | 4 | 1 | |
| (b) | 1 | 3 | 4 | 2 | |
| (c) | 2 | 4 | 3 | 1 | |
| (d) | 1 | 4 | 3 | 2 | |

Ans: (a)

06. For an earth station transmitter, with an antenna output power of 40dBW (10,000W), a back-off loss of 3dB, a total branching and feeder loss of 3dB, a total branching and feeder loss of 3dB and transmit antenna gain of 4dB, the effective isotropic radiated power (EIRP) will be

(a) 38dBW (b) 40 dBW (c) 36 dBW (d) 47 dBW Ans: (a)

07. A coherent binary phase-shift-keyed (BPSK) transmitter operates at a bit rate of 20Mbps. For a probability of error P(e) of 10^{-4} and given carrier-to-noise (C/N) density ratio of 8.8 dB, determine energy of bit-to noise (E_b/N₀) density ratio for a receiver bandwidth equal to the minimum double-sided Nyquist bandwidth.

(a) 23 dB (b) 2.3 dB (c) 8.8 dB (d) 0.88 dB

Ans:(c)

08. An elliptically (arbitrarily) polarized wave can be broken up into
(a) Two circularly polarized components rotating in same direction
(b) Two circularly polarized components rotating in opposite directions

- (c) Two stationary circularly polarized components
- (d) None of these

Ans: (b)

- 09. Klystron operation is based on the principle of
 - (a) Velocity modulation
 - (c) frequency modulation

- (b) Amplitude modulation
- (d) Phase modulation

Ans: (a)

- 10. The following is not an application of varactor diode:
 (a) Parametric amplifier
 (b) Free
 (c) Mathematication (d) Phase
 - (c) Voltage controlled oscillator
- (b) Frequency tuner(d) Phase shifter

- **Ans : (d)**
- 11. The following quantity is not required in the calculation of Q of a cavity resonator(a) Energy stored(b) Power dissipated
 - (c) Loss in radiation

(d) Dimensions of the cavity

Ans: (c)

- 12. When electromagnetic waves are propagated in a waveguide
 - (a) They travel along the walls of the waveguide
 - (b) They travel through the dielectric without touching the walls
 - (c) They are reflected from the walls but do not travel along the walls
 - (d) None of these

Ans : (b)

- 13. Slotted line with tunable probe is not used to measure
- (a) VSWR (b) Wavelength (c) Power (d) Impedance **Ans : (c)**

14. In a microwave magic-T, E plane and H plane are (d) 90° out of phase (b) Out of phase (c) Isolated (a) In phase

Ans: (c)

- 15. Baratters and bolometers are used for measurement of (a) VSWER (b) Transmission losses (c) Microwave power
 - (d) Frequency

- Ans: (c)
- 16. Magnetic properties of ferrites result mainly from
 - (a) Polarization of electromagnetic waves
 - (b) Dielectric behaviour of ferrite
 - (c) Magnetic dipole moment associated with the electron spin
 - (d) External magnetic fields

Ans: (c)

- 17. A communication link is to be set up better two stations 100km as part using $\frac{\lambda}{2}$ antenna to transmit 1kW power. The operating frequency is 100 MHz and the directivity of the two antennae is 1.64. The maximum received power would be (b) 1.53×10^{-8} W (c) 6.12×10^{-9} W (a) 3.06×10^{-8} W (d) 1×10^{-9} W Ans: (b)
- 18. In the ionosphere layer, the lowest frequency signal that penetrates the layer upon vertical incidence is given by
- (a) $f_L = 81 N_{Max}$ (b) $f_L = 81 N_{Max}^2$ (c) $f_L = \sqrt{81N_{Max}}$ (d) $f_L = 81\sqrt{N_{Max}}$ Ans: (c)

19. An 8085 microprocessor executes the following instructions: Two numbers are represented in signed 2's complement form as P = 11101101 and Q = 11100110If Q is subtracted from P, the value obtained in signed 2's complement form is (a) 100000111 (b) 00000111 (c) 11111001 (d) 011111001 Ans: (b)

20. If $(11X1Y)_8 = (12C9)_{16}$ then the values X and Y are (a) 5 and 1 (b) 5 and 7 (c) 7 and 5

(d) 1 and 5

No Answer (The correct answer is X = 3, Y = 1)

21. A mall code of 8085 as given below, is executed MVI A, 7FH ORA A CPI A2H The contents of the accumulator and flags after execution are (a) A = DD, S = 1, Z = 0, CY = 0(b) A = 7F, S = 1, Z = 0, CY = 1(c) A = DD, S=0, Z=1, CY=0(d) A = 7F, S = 0, Z = 1, CY = 1Ans: (b)

22. Following program finds absolute value of N: MVI A, N ORA A JM ONE OUT 01H HLT ONE: (P) (Q) OUT 01H HLT The instructions of (P) and (Q) must be (b) CMC and ADI 0H (a) CMA and ADI 0H (c) INR A and CMC (d) INR A and CMA Ans: (a) An Intel 8085 processor is executing the program given below: 23. **MVI A**, 10H **MVI B, 10H** BACK : NOP ADD B **RLC** JNC BACK HLT The number of times that the operation NOP will be executed as (d) 4 (a) 1 (b) 2 (c) 3Ans: (c) 24. Match List I with List II and select the correct answer using the code given below the lists : List II List I A. Immediate 1. LDA 30FF B. Implicit addressing 2. MOV A, B C. Register addressing 3. LXI H, 2050 D. Direct addressing 4. RRC

Codes:

| Coues: | | | | | |
|--------|---|---|---|---------|------|
| | А | В | С | D | |
| (a) | 3 | 4 | 2 | NCE 100 | 5 |
| (b) | 1 | 4 | 2 | 3CE 193 | J.J. |
| (c) | 3 | 2 | 4 | 1 | |
| (d) | 1 | 2 | 4 | 3 | |
| (a) | | | | | |

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Ans: (a)
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25. The Boolean equation $X = [(A + \overline{B})(B + C)]B$ can be simplified to

(a) $X = \overline{AB}$ (b) $X = A\overline{B}$ (c) X = AB (d) $X = \overline{A}\overline{B}$ Ans: (c)

| 26. | For 8086 microprocessor, the jump distance in bytes for short jump range is (a) Forward 255 and Backward 256 (b) Forward 127 and Backward 128 (c) Forward 31 and Backward 32 (d) Forward 15 and Backward 16 | | | | | | | |
|-----|---|--|--|--|--|--|--|--|
| Ans | : (b) | | | | | | | |
| 27. | The action performed by the following instruction of 8086: mov [1234h], AX (a) Move contents of memory location 1234h to register AX (b) Move the contents of register AX to memory offset 1234h (c) Add contents at 1234h and AX (d) Add contents of 1234h and AX and store the result in 1234h | | | | | | | |
| Ans | :(b) seering | | | | | | | |
| 28. | While executing a program, 8085 microprocessor completes fetching of instruction JMP 2050 stored at address 2057H. The contents of the program counter after fetching the instruction would be | | | | | | | |
| Ans | (a) 2050H (b) 2057 H (c) 205A H (d) 2051 H (c) | | | | | | | |
| | | | | | | | | |
| 29. | For Opcode fetch operation in 8085 microprocessor (a) $S_1 = 0, S_2 = 1 \overline{RD} = 0$, ALE high in T_1 (b) $S_1 = 1, S_2 = 1 \overline{RD} = 0$, ALE high in T_1 | | | | | | | |
| | (a) $S_1 = 0, S_2 = 1 RD = 0, ALE high in T_1$ (b) $S_1 = 1, S_2 = 1 RD = 0, ALE high in T_2$ (c) $S_1 = 1, S_2 = 1, RD = 0, ALE high in T_2$ (d) $S_1 = 0, S_2 = 1 RD = 0, ALE high in T_2$ | | | | | | | |
| Ans | (c) z_1 (c) z_1 (c) z_1 (c) z_1 (c) z_2 (c) z_2 (c) z_2 (c) z_1 (c) z_2 (c) z | | | | | | | |
| 30. | In a microprocessor, the service routine for a certain interrupt starts from a fixed location of memory which cannot be externally set, but the interrupt can be delayed or rejected. Such an interrupt is | | | | | | | |
| | (a) Non- maskable and non-vectored (b) Maskable and non-vectored (c) Maskable and vectored | | | | | | | |
| Ans | (c) Non-maskable and vectored (d) Maskable and vectored : (d) | | | | | | | |
| 31. | A memory system has a total of 8 memory chips, each with 12 address lines and 4 data | | | | | | | |
| 51. | lines. The size of the memory system is | | | | | | | |
| Δns | (a) 16k bytes (b) 32k bytes (c) 48 k bytes (d) 64k bytes (a) | | | | | | | |
| | | | | | | | | |
| 32. | Consider the following statements for a DRAM: 1. Bit is stored as a charge. 2. It is made of MOS transistors. 3. Speed of DRAM is faster than processors. 4. Each memory cell requires six transistors Which of these statements are correct | | | | | | | |
| Ans | (a) 1 and 2 only (b) 2 and 3 only (c) 3 and 4 only (d) 1,2,3 and 4 : (a) | | | | | | | |

33. The access time of a cache memory is 100ns and that of main memory is 1 ms.80% of the memory requests are for read and others are for write. Hit ratio for read only accesses is 0.9. A write through procedure is used. The average access time of the system for both read and write requests is

(a) 200 ns
(b) 360 ns
(c) 720 ns
(d) 1100ns

| 34. | A virtual memory syste words and page and blo words. The number of p 10246215700 | ock sizes of 1k word age faults using LRU | s. The number of pag- policy, for following p | e faults using of 1k bage references is |
|-------------------|--|--|--|--|
| | | (b) 7 | (c) 9 | (d) 10 |
| Ans | : (a) | | | |
| 35. | Among memory types, t (a) Multi port Dynamic (b) Multipoint Dynamic (c) Multipoint Disk Ran (d) Multi port Dimensio | Random Access Mem Random Access Men dom Access me <mark>m</mark> ory | nory | |
| Ans | • • | | leniory | |
| | | | | |
| 36. | The following register h | olds the instruction be | efore it goes to the dec | oder: |
| | | (b) Accumulator | (c) Address register | (d) Data register |
| Ans 37. | : (d) The incorrect match (wh (a) SISD Model of comp (b) SIMD Model of comp (c) MISD Model of comp (d) MIMD model of comp | puter : 1 cont nputer : 1 cont nputer : n cont | rol unit and 1 ALU rol unit and n ALUs rol units and n ALUs rol units and 1 ALU | |
| Ans | | | | |
| 38. Ans | | ion dependent , the mo (b) Indirect mode | ost suitable addressing (c) Relative mode | mode is (d) Indexed mode |
| | | | | |
| 39. | The data structure neede | ed to convert infix not | ation to prefix notation | i is |
| | (a) Queue | (b) Stack | (c) Tree | (d) Graph |
| Ans | : (b) | SINCE | 1995 | |
| 40 | A him own fur - The - 1 | | | Τ÷α |
| 40. | A binary tree T ha n leaf | | e e | |
| | (a) $\log_2 n$ | (b) n –1 | (c) n | (d) 2^{n} |

- Ans: (b)
- 41. In locations where the humidity is low, ICs based on one of the following technologies should be handled only after grounding the body. The technology is (a) TTL (b) CMOS (c) DTL (d) I²L
 Ans : (b)

42. If a feedback control system has its open-loop transfer function

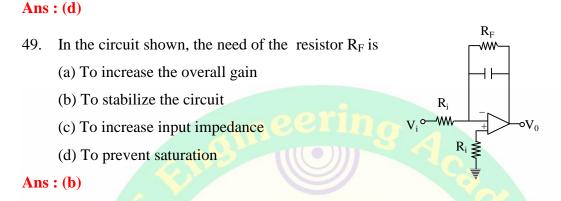
 $G(s)H(s) = \frac{K}{[s(s+2)(s^{2}+2s+5)]}$ the coordinates of the centroid of the asymptotes of its root-locus are (a) -1 and 0 (b) 1 and 0 (c) 0 and -1(d) 0 and 1 Ans: (a)

- 43. Match List I with List II and select the correct answer using the code given below the lists:

| | Lis | <u>List I</u> | | | List II | | | | | |
|-----|-------------------------------|---------------------------------|----------------------|-----------------------------|--------------|--|--|--|--|--|
| | A. HTL | | | 1. High fan-out | | | | | | |
| | - | OMOS | | 2. H | ighest spe | ed of operation | | | | |
| | \mathbf{C} . \mathbf{I}^2 | L | | 3. H | igh noise | immunity | | | | |
| | D. E | CL | | 4. Lo | owest pro | duct power and delay | | | | |
| | Code | e: 🖊 🏑 | | | | | | | | |
| | | A | В | C | D | | | | | |
| | (a) | 3 | 4 | 1 | 2 | | | | | |
| | (b) | 2 | 4 | 1 | 3 | | | | | |
| | (c) | 3 | 1 | 4 | 2 | | | | | |
| | (d) | 2 | 1 | 4 | 3 | | | | | |
| An | s : (c) | | | | | | | | | |
| | | | - | | | | | | | |
| 44. | | - | | | c family is | given by | | | | |
| | . , | ain band | - | | | | | | | |
| | (b) (l | Propagati | on delay | time) × (Power dissipation) | | | | | | |
| | (c) (I | Fan-out)× | (Propag | gation of | | | | | | |
| | (d) (l | Noise –m | argin) × | (Powe | er dissipati | on) | | | | |
| An | s : (b) | | | | | and the second sec | | | | |
| | | | | | | And the second sec | | | | |
| 45. | The o | correct ex | pression | i is | | | | | | |
| | (a) \overline{A} | $\overline{AB} + A\overline{B}$ | $=\overline{AB}(A$ | + B) | | (b) $\overline{AB} + \overline{AB} = AB(\overline{A} + \overline{B})$ | | | | |
| | (c) \overline{A} | $\overline{AB} + A\overline{B}$ | $= AB(\overline{A})$ | $+\overline{B}$ | | (d) $\overline{AB} + \overline{AB} = \overline{AB}(A+1)$ | | | | |
| An | s : (a) | | | | | and a | | | | |
| | | | | | | | | | | |
| 46. | Bina | ry data i | s being | repres | ented in | size of byte and in 2's complement form. The | | | | |
| | numl | ber of 0's | present | in repr | esentation | n of (-127) _{DECIMAL} IS | | | | |
| | (a) 8 | | (b) 7 | 5 | NG | (c) 6 (d) 5 | | | | |
| An | s : (c) | | | | | | | | | |
| | | | | | | | | | | |
| 47 | Sim | lified for | m of the | logic | expression | ı | | | | |

47. Simplified form of the logic expression $(A + \overline{B} + C)(A + \overline{B} + \overline{C})(A + B + C)$ is (a) $\overline{AB} + \overline{C}$ (b) $A + \overline{BC}$ (d) $AB + \overline{C}$ (c) A Ans: (b)

48. For a transistor used as a switch, t_d is delay time, t_r is rise time, t_s is storage time and t_f is fall time. Then turn-on time t_{ON} and turn-off time t_{OFF} are respectively (a) $(t_d + t_s)$ and $(t_r + t_f)$ (b) $(t_d + t_f)$ and $(t_s + t_r)$ (c) $(t_r + t_s)$ and $(t_d + t_f)$ (d) $(t_d + t_r)$ and $(t_s + t_f)$



50. A 40V dc supply is connected across the network comprising of zener and silicon diode as shown. The regulated voltages V_{01} , V_{02} and source current I_s are

40V

1.5K

 V_{02}

- (a) 2.4V, 5.1 V and 21.7mA
- (b) 3V,6V and 22.7mA
- (c) 3.3V, 9.3V and 20.5mA
- (d) 4V, 10V and 20mA



- 51. For a full wave rectifier, with sinusoidal input and inductor as filter, ripple factor for maximum load current and minimum load current conditions are respectively (a) 0.1 and 1 (b) 0.1 and 0.47 (c) 0 and 0.47 (d) 0 and 0.22
 Ans: (c)
- 52. The second-harmonic component in the output of a transistor amplifier, without feedback, is B₂. The second harmonic component, with negative feedback B₂ is equal to (where A = Amplifier gain and β = feedback factor)

(a)
$$\frac{B_2}{1 + A\beta}$$
 (b) $B_2 (1 + A\beta)$ (c) $\frac{B_2}{\beta}$ (d) $\frac{B_2}{A\beta}$
(e) (a)

- **Ans : (a)**
- 53. The lower 3dB frequency of an n-stage amplifier with non-interacting stages is given by

(a)
$$\frac{f_L}{\sqrt{2^{\frac{1}{n}} - 1}}$$
 (b) $f_L \left[\sqrt{2^{\frac{1}{n}} - 1} \right]$ (c) $\frac{f_L}{\sqrt{2^{\frac{1}{n}} - n}}$ (d) $f_L \left[\sqrt{2^{\frac{1}{n}} - n} \right]$

Where f_L is the 3dB frequency of a single stage.

Ans: (a)

54. An output signal of a power amplifier has amplitudes of 2.5V fundamental, 0.25V second harmonic and 0.1V third harmonics. The total percentage harmonic distortion of the signal is (a) 12.8% (b) 10.8% (c) 6.4% (d) 1.4%

Ans: (c)

55. A change in the value of the emitter resistance R_e in a differential amplifier

- (a) Affects the difference mode gain, A_d
- (b) Affects the common mode gain, A_C
- (c) Affects both A_d and A_c
- (d) Does not affect either A_d or A_c

Ans: (b)

In a transistor biased in the active region, thermal runway is due to 56.

- (a) Base emitter voltage V_{BE} which decreases with rise in temperature
- (b) Change in reverse collector saturation current due to rise in temperature
- (c) Heating the transistor
- (d) Changes in β which increases with temperature

Ans: (b)

57. A transistor is said to be useful to be configured as an amplifier when its β is (b) Between 0 and 1 (c) Between 1 and 50 (d) > 50 (a) less than 0

Ans: (d)

- 58. A BJT is biased with a power supply of 12V. For minimum heat dissipation, the drop across the transistor will be
- (a) 6V (b) 9V (c) 12V (d)> 9V but < 12VAns: (a)
- A bipolar junction transistor with forward current transfer ratio $\alpha = 0.98$, when working 59. in CE mode, provides current transfer ratio β as (b) 0.02(c) 49 (d) 0.49

(a) 98

- Ans: (c)
- 60. Match List I with List II and select the correct answer using the code given below the lists:

| | List | I | | | List II |
|--------|----------|-------------------|---------|------|-------------------|
| A. Tur | ned circ | 1. Schottky diode | | | |
| B. Vol | tage ret | ference | S | | 2. Varactor diode |
| C. Hig | h frequ | ency sv | vitch | | 3. PIN diode |
| D. Cui | rrent co | ntrolled | attenua | ıtor | 4. Zener diode |
| Code: | | | | | |
| | Α | В | С | D | |
| (a) | 2 | 4 | 1 | 3 | |
| (b) | 3 | 4 | 1 | 2 | |
| (c) | 2 | 1 | 4 | 3 | |
| (d) | 3 | 1 | 4 | 2 | |
| 2 N | | | | | |

Ans: (a)

61. Assuming that only logic inputs X and Y are available and their complements X̄ and Ȳ are not available, the minimum number of two-input NAND gates required to implement X ⊕ Y would be

(a) 2
(b) 3
(c) 4
(d) 5

Ans: (c)

62. The minimum number of NAND gates required to implement $A + A\overline{B} + A\overline{B}C$ is equal to (a) Zero (b) 1 (c) 4 (d) 7

Ans: (a)

63. The type of device used to interface a parallel data format with external equipment's serial format is
(a) Key matrix
(b) UART
(c) Memory chip
(d) Serial-in, parallel –out

64. A bistable multi-vibrator that functions as a voltage comparator with hysteresis is called (a) T flip-flop (b) D flip-flop (c) J-K flip-flop (d) Schmitt trigger
Ans: (d)

65 The characteristic equation of the T lfip-flop is given by (a) $Q_{n+1} = TQ_n$ (b) $Q_{n+1} = T\overline{Q}_n + Q_n\overline{T}$ (c) $Q_n + 1 = \overline{T}Q_n$ (d) $Q_{n+1} = T\overline{Q}_n$

Ans: (b)

66. A pulse train with a frequency of 1MHz is counted using a mod-1024 ripple counter built with J-K flip-flops. For proper operation of the counter the maximum permissible propagation delay per flip-flop stage is

(a) 100ns (b) 50 ns (c) 20 ns Ans : (a) (d) 10ns

67. The highest speed counter is(a) Asynchronous counter(c) Ripple counter

(b) Synchronous counter (d) Ring counter

Ans: (b)

68. An analog voltage of 3.41V is converted into 8-bit digital form by an A/D converter with a reference voltage of 5V. The digital output is

(a) 1001 1001
(b) 1111 0001
(c) 1011 0111
(d) 1010 1110

Ans: (d)

69. Match list I with List Ii aqnd select the correct answer using the code given below the lists:

| 11515. | | | | | | | | | |
|---------------|--|--|---|--|--|--|--|--|--|
| <u>List I</u> | | | | <u>List II</u> | | | | | |
| A. 555 | | | 1. M | licrocontro | oller | | | | |
| B. 7417 | '3 | | 2. R | egister | | | | | |
| C. 7416 | 53 | | | | | | | | |
| D. 8097 | 7 | | 4. C | ounter | | | | | |
| Code: | | | | | | | | | |
| | Α | В | С | D | | | | | |
| (a) | 3 | 4 | 2 | 1 | | | | | |
| | 1 | 4 | 2 | 300 | | | | | |
| | 3 | 2 | 4 | 1 | | | | | |
| | 1 | 2 | 4 | 3 | | | | | |
| : (c) | | | | | | | | | |
| | List I A. 555 B. 7417 C. 7416 D. 8097 Code: (a) (b) (c) (d) | $ \frac{\text{List I}}{A. 555} B. 74173 C. 74163 D. 8097 \frac{\text{Code:}}{A} (a) 3 (b) 1 (c) 3 (d) 1 $ | $ \begin{array}{r} \underline{\text{List I}} \\ A. 555 \\ B. 74173 \\ C. 74163 \\ D. 8097 \end{array} $ $ \begin{array}{r} \underline{\text{Code:}} \\ (a) & 3 & 4 \\ (b) & 1 & 4 \\ (c) & 3 & 2 \\ (d) & 1 & 2 \end{array} $ | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ | $\begin{array}{cccccccccccccccccccccccccccccccccccc$ |

- 70. In which of the following type of A/D converter does the conversion time almost double for every bit added to the device?
 - (a) Counter type A/D converter
 - (b) Tracking type A/D converter
 - (c) Single-slope integrating type A/D converter
 - (d) Successive approximation type A/D converter

Ans: (a)

71. If both inputs of S-R NAND latch are low, the output will be

(a) Unpredictable (b) Toggle (c) Reset (d) Remain same **Ans : (a)**

- 72. A 10-bit DAC provides an analog output which has a maximum value of 10.23 volts. Resolution of the DAC is
 - (a) 10 mV (b) 15 mV (c) 20 mV (d) 40 mV

Ans: (a)

- 73. Consider the following statements regarding registers and latches:1. Registers are temporary storage devices, whereas latches are not.2. A latch employs cross-coupled feedback connections.
 - 3. A register stores a binary word, whereas a latch does not.

The correct statement(s) is/are (a) 1 only (b) 2 only (c) 1 and 3 (d) 2 and 3 Ans : (d) 74. Match List I with List II and select the correct answer using the code given below the lists:

| / 4. | lists: | | | | | | |
|------|----------------------------------|----------------------------|---|--|--|--|--|
| | <u>List I</u> | | List II | | | | |
| | A. Flash conver | ter ADC pproximation AD | Integrating type Fast conversion | | | | |
| | D . Successive a | pproximation AL | 2. Past conversion | | | | |
| | C. Counter ramp | p ADC | 3. Maximum conversion clock periods = | | | | |
| | D. Dual slope A | DC | Number of bits 4. Uses a DAC in its feedback path | | | | |
| | | - | | | | | |
| | <u>Codes:</u> A | B C I | portin | | | | |
| | (a) 2 | 3 4 1 | | | | | |
| | (b) 1 (c) 2 | | | | | | |
| | (c) 2 (d) 1 | 4 3 1 4 3 2 | | | | | |
| Ans | : (a) | | | | | | |
| 75. | A 12-bit ADC i | s operating with | a 1 µs clock period and total conversion time is seen to | | | | |
| 15. | be 14 μ s. The A | | a i pis clock period and total conversion time is seen to | | | | |
| | (a) Flash type | | (b) Counting type | | | | |
| Ans | (c) Integrating t : (a) | ype | (d) Successive approximately type | | | | |
| | | | | | | | |
| 76. | The type of sydetermined from | | used for determination of static error constants is | | | | |
| | | in for open loop | transfer function | | | | |
| | (b) Poles at orig | in for open loop | transfer function | | | | |
| | | | p transfer function p transfer function | | | | |
| Ans | (d) i oles at olig : (b) | in for closed loop | | | | | |
| 77. | The time taken | for the output to | actile within ± 20 of star input for the control system | | | | |
| //. | | 25 | settle within $\pm 2\%$ of step input for the control system | | | | |
| | represented by | $s^2 + 5s + 25$ 1s gi | ven by | | | | |
| | (a) 1.2 s | (b) 1.6 s | (c) 2.0 s (d) 0.4 s | | | | |
| Ans | : (b) | | | | | | |
| 78. | | | measure of the transient characteristics of a control | | | | |
| | system, when su 1. Maximum ov | bjected to unit st | ep excitation: 2. Maximum undershoot | | | | |
| | 3. Overall gain | CISHOOL | 4. Delay time | | | | |
| | 5. Rise time | | 6. Fall time | | | | |

13

(a) 1, 3 and 5

Ans: (d)

(b) 2, 4 and 5 (c) 2, 4 and 6 (d) 1, 4 and 5

79. In a feedback control system, if

 $G(s) = \frac{4}{s(s+3)} \text{ and } H(s) = \frac{1}{s}, \text{ then the closed-loop system will be of type}$ (a) 3 (b) 2 (c) 1 (d) 0 s: (d)

Ans : (d)

80. For a second order dynamic system, if the damping ratio is 1 then the poles are
(a) Imaginary and complex conjugate
(b) In the right-half of s-plane
(c) Equal, negative and real
(d) Negative and real

Ans: (c)

- 81. The spectral density and autocorrelation function of white noise is
 - (a) Delta and uniform

(b) Uniform and delta (d) Gaussian and delta

(c) Gaussian and uniform

Ans : (b)

82. The average information associated with an extremely likely message is zero. What is the average information associated with an extremely unlikely message?

- (a) Zero
- (b) Infinity
- (c) Depends on total number of messages
- (d) Depends on speed of transmission of the message

Ans: (b)

- 83. The effect of integral controller on the steady state error (e_{ss}) and on the relative stability (R_s) of the system are
 - (a) Both are increased

- (b) e_{ss} is increased but R_s is reduced (d) Both are reduced
- (c) e_{ss} is reduced but R_s is increased
- Ans : (d)
- 84. A proportional integral (PI) controller results in which of the following?
 - (a) Improves the transient response without affecting steady state response
 - (b) Improves the steady state response without affecting transient response
 - (c) Improves both transient response and steady state response
 - (d) Improves the steady state response while marginally affecting transient response, for well designed control parameters

Ans: (d)

85. A liquid level controller linearly converts a displacement of 2 m to 3 m into 4–20 mA control signal. A relay serves as two position controller to open and close an inlet valve. Relay closes at 12 mA and opens at 10 mA. The hysteresis zone is

(a) 0.1 m (b) 0.125 m (c) 0.15 m (d) 0.2 m Ans : (c)

- 86. The necessary conditions for poles and zeros of the transfer function of a bridge-T network containing only resistors and capacitors and used as a compensator are
 - (a) All the poles and zeros must be imaginary
 - (b) Poles and zeros both can be complex
 - (c) Poles can be complex but zeros must be real
 - (d) Zeros can be complex but poles must be real

Ans: (d)

- 87. Considering the filtering property, the lead compensators and lag compensators are categorized respectively as (a) Low pass and high pass filters (b) High pass and low pass filters
 - (c) High pass and high pass filters

- (d) Low pass and low pass filters

88. Match List I with List II and select the correct answer using the code given below the lists:

| | insts: | | | | | | | | | | | |
|-----|---|-----------------------------------|--------------------|-------------|-----------|----------------|---------|---|--------------------|-------------|--------------------|--------|
| | <u>List I</u> | | | | | <u>List II</u> | | | | | | |
| | A. PI co | | | | | | ay cont | | | | | |
| | B. PD c | ontrol | | | | 2. Lea | d lag c | ompen | sator | | | |
| | C. PID o | control | | | | 3. Lea | d comp | pensato | r | | | |
| | D. On-o | off conta | rol | | | 4. Lag | comp | ensator | | | | |
| | | | | | | | | | | | | |
| | Codes: | | | | | | | | | | | |
| | | Α | B 2 3 | C 3 2 | D | | | Α | B 2 3 | C 3 2 | D | |
| | (a) | 4 | 2 | 3 | 1 | 1 | (b) | 1 | 2 | 3 | 4 | |
| | (c) | 4 | 3 | 2 | 1 | | (d) | 1 | 3 | 2 | 4 | |
| Ans | : (c) | | | | | | | | | | | |
| | | | | | | | | | | | | |
| 89. | A phase | lead c | ompens | atino n | etwork | has its tr | ansfer | functio | $n G_{1}(s)$ | _ 10(1 | +0.04s) -0.01s) | . The |
| 07. | ri phuse | | ompene | ading n | etwork . | nus nus en | unsion | runetie | | (1+ | - 0.01s) | · The |
| | maximu | m phas | se lead | occurs a | at a freq | uency of | | | | | | |
| | (a) 50 ra | nd/s | | (b) 2 | 5 rad/s | | (c) 10 |) rad/s | | (d) 4 | rad/s | |
| Ans | : (a) | | | | | | | | | | | |
| | | | | | | | | | | | | |
| 90. | A third | order s | system | is appi | oximate | ed to an | equiva | lent se | cond of | rder sys | stem. The | e rise |
| | time of | this app | oroxima | ated sys | tem wil | l be | | | | | | |
| | (a) Same as the original system for any input | | | | | | | | | | | |
| | (b) Smaller than the original system | | | | | for any in | put | | | | | |
| | (c) Larger than the original syste | | | | stem fo | or any inp | out | | | | | |
| | (d) Sma | ller or l | larger d | ependi | ng on th | e type of | input | | | | | |
| Ans | : (b) | | | w, | | | | 1. 5 | | | | |
| | | | | | | | | ~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~ | | | | |
| 91. | | | | | | =1, in C | b-plane | e is giv | en by th | ne follo | wing equ | ation |
| | where x | $= \operatorname{Re}[\mathbf{C}]$ | G(jω)] | and y = | Im[G(j | ω)] | - | 2 | | | 2 2 | |
| | $\langle \rangle$ | 0 5 | | (1) | 0 | | () 2 | | 0.05 | (1) | 2.21 | 1 |

- (d) $x^2 + y^2 = 1$ (c) $x^2 + y^2 = 0.25$ (a) x = -0.5(b) x = 0Ans: (a)
- 92. All the constant N loci in G-plane intersect the real axis in points (a) –1 and origin (b) -0.5 and +0.5(c) -1 and +1(d) Origin and +1 Ans: (a)
- 93. For a unity feedback control system, if its open-loop transfer function is given by G(s) $H(s) = \frac{10}{(s+5)^3}$, then its gain margin will be (b) 40 dB (a) 20 dB (c) 60 dB (d) 80 dB Ans: (b)

Ans: (b)

| 94. | The gain cross-over fre | quency and phase mar | gin of the transfer func | tion $\frac{1}{s(s+1)}$ are |
|--|--|------------------------------------|-------------------------------|--|
| | (a) 1 rad/s and 45^0 | | (b) 2 rad/s and 45^{0} | 5(5 + 1) |
| | (c) 2 rad/s and 135° | | (d) 1 rad/s and 135° | |
| Ans | : (a) | | | |
| 05 | | 1 C | | 11.1 1 C |
| 95. | For a type 1 system, the (a) 0 dB/decade | | (c) 20 dB/decade | - |
| Ans | (a) 0 ub/decade | (b) 0 uD/decade | (c) 20 ub/uecaue | $(\mathbf{u}) = 20 \mathbf{u} \mathbf{D} / \mathbf{u} \mathbf{c} \mathbf{c} \mathbf{a} \mathbf{u} \mathbf{c}$ |
| | | | | |
| 96. | The characteristic equa damping ratio δ will be | 2 neeri | | |
| | (a) $\delta = 0$ | (b) $0 < \delta < 1$ | (c) $\delta = 1$ | (d) $\delta > 1$ |
| Ans | : (a) | | | |
| 07 | | | | |
| 97. | If root loci plots of a pa point, then the gain mat | | | naginary axis at any |
| | (a) Zero | (b) 0.707 | (c) 1.0 | (d) Infinite |
| Ans | : (d) | | (0) 1.0 | |
| | | | | |
| 98. | A system is described | by the transfer function | $n G(s) = \frac{2s+5}{s+5}$ | The dc gain of the |
| 70. | Tr system is described | by the transfer function | (s+5)(s+4) | . The de gain of the |
| | system is | | | |
| | (a) 0.25 | (b) 0.5 | (c) 1 | $(d) \infty$ |
| Ans | : (a) | | | |
| 99. | The sensitivity $S_{T}(K)$ o | f transfer function | | |
| <i>,</i> ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,, | | | | |
| | $T = \frac{(1+2K)}{(3+4K)}$ with resp | bect to the parameter K | is given by | |
| | | | 217 | |
| | (a) $\frac{K}{3+K^2}$ | mary & | (b) $\frac{3K}{2+4K+K^2}$ | |
| | 2K | ~ | 4K | |
| | (c) $\frac{2K}{3+10K+8K^2}$ | | (d) $\frac{4K}{2+5K+7K^2}$ | |
| Ans | : (c) | | | |
| 100 | | (1 '1') C '' C | 11 1 / 1 | 1 |
| 100 | The range of K for s | | edback system whose | open-loop transfer |
| | function is $G(s) = \frac{1}{c(s)}$ | $\frac{\mathbf{x}}{\mathbf{x}}$ is | 1995 | |

function is $G(s) = \frac{1}{s(s+1)(s+2)}$ is **1990** (a) 0 < K < 3 (b) 0 < K < 6 (c) K > 6 (d) 0 > K > 3**Ans : (b)** 101. For the 8085 assembly language program given below, the content of the accumulator after the execution of the program is

| after the execution of | | | |
|---------------------------------------|--------------------------|-------------------------|--|
| 3000 MVI | A, 45H | | |
| 3002 MOV | VB, A | | |
| 3003 STC | | | |
| 3004 CMC | 2 | | |
| 3005 RAR | | | |
| 3006 XRA | АВ | | |
| 3007 HLT | | | |
| | | | |
| (a) 00 H | (b) 45 H | (c) 67 H | (d) E7 H |
| Ans : (c) | | | $(\mathbf{u}) \ge \mathbf{v} = \mathbf{u}$ |
| | | | |
| 102. The 8254 Programmal | ble Interval Timer is se | t to work in MODE 5. | The following would |
| best describe its funct | | | |
| (a) Software triggered | | (b) Hardware trigge | red strobe |
| (c) Square wave gener | | (d) Interrupt on term | |
| Ans: (b) | | (u) interrupt on terr | |
| | | | |
| 103. To configure port A | and port B as output | ports, port C not be | ing used in the 8155 |
| | ce, the control word sh | | |
| (a) 03H | (b) 01H | (c) 02H | (d) 60H |
| Ans : (a) | (0) 0111 | (0) 0211 | (4) 0011 |
| · · · · · · · · · · · · · · · · · · · | | | |
| 104. The 8085 microproces | sor instructions with r | equired number of T s | tates are given below |
| Which pair is correctl | | equired number of 1 s | |
| - | - | PHL : 6 T-9 | states |
| | states (d) S | | -states |
| Ans : (b) | states (u) b | | states |
| · · · · · · · · · · · · · · · · · · · | | | |
| 105. The crystal frequency | of 8085 microprocess | sor is 6 MHz. The tim | e required to execute |
| | er this microprocessor i | | le required to execute |
| | (b) 10.67 µsec | | (d) 8.67 µsec |
| Ans : (a) | (b) 10.07 µsee | (0) 1.55 µ500 | (u) 0.07 µsee |
| · · · · · · · · · · · · · · · · · · · | | 1 som man | |
| 106. In 8085 microprocess | or after the execution | of RST 5 instruction | the program control |
| shifts to | in, and the execution | T OF ROT 5 HIST detroit | , the program control |
| (a) 0030 H | (b) 0005 H | (c) 0028 H | (d) 0024 H |
| Ans : (c) | (0) 0003 11 | (0) 0020 11 | (u) 002411 |
| Ans · (c) | SINCE | 1995 | |
| 107. Consider the followin | a 8085 interrupte | | |
| 1. TRAP | g 0005 interrupts. | 2. INTR | |
| 3. RST 6 | | 4. RST 7.5 | |
| 5. RST 0 | | 4. K51 7.3 | |
| | te ara | | |
| The software interrup | | | |
| | | | |
| (a) 1 and 3 only | (b) 2 and 5 only | (c) 3 and 5 only | (d) $1 2 3 4$ and 5 |
| (a) 1 and 3 only $Ans: (c)$ | (b) 2 and 5 only | (c) 3 and 5 only | (d) 1,2,3,4 and 5 |
| (a) 1 and 3 only Ans : (c) | (b) 2 and 5 only | (c) 3 and 5 only | (d) 1,2,3,4 and 5 |

Directions: Each of the next thirteen (13) items consists of two statements, one labelled as the 'Statement (I)' and the other as 'Statement (II)'. You are to examine these two statements carefully and select the answers to these items using the codes given below: **Codes:**

| | • • | | atement (I) and Statement (II) are individually true and Statement (II) prrect explanation of Statement (I) |
|------|-------------------|--------------------|---|
| | (b) l | Both Sta | atement (I) and Statement (II) are individually true but Statement (II) ne correct explanation of Statement (I) |
| | (c) S | Stateme | nt (I) is true but Statement (II) is false |
| | (d) S | Stateme | nt (I) is false but Statement (II) is true |
| 108. | | t (II) : | In a transistor designed to be used for power amplification, the collector size is largest relative to the emitter and base. The collector is connected to the body of the transistor and hence to a heat sink for heat dissipation to be effective. |
| Ans | : (a) | 4 | icat sink for heat dissipation to be effective. |
| 109. | | t (II) : 7 | The carry look-ahead adder is a fast adder The carry look-ahead adder generates the carry and the sum digits directly. |
| Ans | : (a) | | |
| 110. | | t (II) : I נ | Root loci are symmetrical with respect to real axis of the s-plane. Root loci are normally symmetrical with respect to the perpendicular axis of symmetry of the pole-zero combination of the loop transfer function. |
| Ans | : (c) | | unction. |
| 111. | Statement | 1 | Nyquist criterion is a powerful tool to determine stability of a closed oop system using open loop transfer function. |
| | Statemen | | Nyquist criterion relates the locations of poles and zeros of the closed loop transfer function. |
| Ans | : (c) | 6 | |
| 112. | Statement | | A second order system subjected to a unit impulse oscillates at its natural frequency. |
| Ans | Statemen : (d) | t (II) : 1 | Impulse input contains frequencies from $-\infty$ to $+\infty$. |
| 113. | Statement | e | All the systems which exhibit overshoot in transient response will also exhibit resonance peak in frequency response. |
| | | | A large resonance peak in frequency response corresponds to a large povershoot in transient response. |
| Ans | : (a) | | |
| 114. | | i | In a prototype second order system the rise time t_r and bandwidth are inversely proportional. |
| | Statemen | t (II) : 1 | Increasing ω_n increases bandwidth while t_r reduces. |
| Ans | • (a) | | |

Ans: (a)

| in | he phase angle plot in Bode diagram is not affected by the variation open loop gain of the system. he variation in gain of the system has no effect on the phase margin. |
|---------------------------|--|
| co Statement (II) : FN | M spectrum consists of a carrier and an infinite number of side band omponents. M signals are used only in TV transmission to ensure better picture nality. |
| Ans: (c) | |
| ma | the two body system consisting of the earth and a satellite, centre of ass always coincides with centre of the earth. Tass of earth is much greater than mass of satellite. |
| ne Statement (II) : Ga | unn effect device is a slice made from n-doped GaAs and provides egative resistance characteristics. aAs has an empty energy band higher in energy than the filled or artly filled bands. |
| Statement (II) : Lo | ower output of the lowest mode in a reflex klystron is maximum. ower modes occur at higher repeller voltages where the acceleration bunched electrons on return is maximum. |
| teo | ne DMA technique is more efficient than the Interrupt-driven chnique for high volume I/O data transfer. ne DMA technique does not make use of the Interrupt mechanism. |

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